

Komponen z :

$$\frac{\partial}{\partial t} \rho v_z = - \left(\frac{\partial}{\partial x} \rho v_x v_z + \frac{\partial}{\partial y} \rho v_y v_z + \frac{\partial}{\partial z} \rho v_z v_z \right) - \left(\frac{\partial}{\partial x} \tau_{xz} + \frac{\partial}{\partial y} \tau_{yz} + \frac{\partial}{\partial z} \tau_{zz} \right) - \frac{\partial p}{\partial z} + \rho g_z$$

Untuk sistem koordinat spheris & silindris lihat

Untuk shearstress Newtonian fluids; koord. Cartesian + tabel

$$\tau_{yx} = \tau_{xy} = -\mu \left[\frac{\partial v_x}{\partial y} + \frac{\partial v_y}{\partial x} \right]$$

$$\tau_{yz} = \tau_{zy} = -\mu \left[\frac{\partial v_y}{\partial z} + \frac{\partial v_z}{\partial y} \right]$$

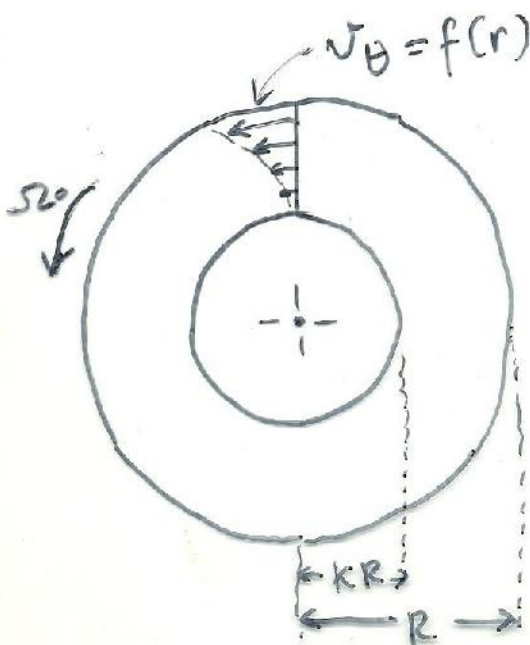
$$\tau_{zx} = \tau_{xz} = -\mu \left[\frac{\partial v_z}{\partial x} + \frac{\partial v_x}{\partial z} \right]$$

Koordinat yg lain lihat tabel 3.4-6, 3.4-7

PENERAPAN

Contoh 3.5-1

Tangential Annular Flow of a Newtonian Fluid.



Fluida Newton (ρ, μ tetap) berada antara 2 silinder koaksial; silinder luar bergerak dgn kecep. sudut tetap, Ω_0 dan silinder dlm diam. Kondisi steady state, fluida bergerak laminar.

Cari $v_\theta = f(r)$

End efek diabaikan.

Asumsi z : (summary)

1. steady state
2. laminar, ρ tetap
3. Newtonian fluid, μ tetap
4. $v_r = v_z = 0$; $\frac{\partial p}{\partial \theta} = 0$

Gunakan Tabel 3.4.1 \rightarrow pers. kontinuitas

Koord. silinder

$$\frac{\partial p}{\partial t} + \frac{1}{r} \frac{\partial}{\partial r} (\rho r v_r) + \frac{1}{r} \frac{\partial}{\partial \theta} (\rho v_\theta) + \frac{\partial}{\partial z} (\rho v_z) = 0$$

Plm v. komp. r =

$$\rho \left(\frac{\partial v_r}{\partial t} + v_r \frac{\partial v_r}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_r}{\partial \theta} - \frac{v_\theta^2}{r} + v_z \frac{\partial v_r}{\partial z} \right) = - \frac{\partial p}{\partial r}$$

$$+ \mu \left[\frac{\partial}{\partial r} \left(\frac{1}{r} \frac{\partial}{\partial r} (r v_r) \right) + \frac{1}{r^2} \frac{\partial^2 v_r}{\partial \theta^2} - \frac{2}{r^2} \frac{\partial v_\theta}{\partial \theta} + \frac{\partial^2 v_r}{\partial z^2} \right]$$

$$+ \rho g_r \quad \dots \rightarrow \quad \rho \frac{v_\theta^2}{r} = \frac{\partial p}{\partial r} \quad \dots (1)$$

komp. $\theta =$

$$\rho \left[\frac{\partial v_\theta}{\partial t} + v_r \frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{v_r v_\theta}{r} + v_z \frac{\partial v_\theta}{\partial z} \right] = - \frac{1}{r} \frac{\partial p}{\partial \theta}$$

$$+ \mu \left[\frac{\partial}{\partial r} \left(\frac{1}{r} \frac{\partial}{\partial r} (r v_\theta) \right) + \frac{1}{r^2} \frac{\partial^2 v_\theta}{\partial \theta^2} + \frac{2}{r^2} \frac{\partial v_r}{\partial \theta} + \frac{\partial^2 v_\theta}{\partial z^2} \right]$$

$$+ \rho g_\theta \quad \neq f(\theta)$$

$$\mu \left[\frac{d}{dr} \left(\frac{1}{r} \frac{d}{dr} (r v_\theta) \right) \right] = 0 \quad \dots (2)$$

komp. z:

$$\rho \left[\frac{\partial v_z}{\partial t} + v_r \frac{\partial v_z}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_z}{\partial \theta} + v_z \frac{\partial v_z}{\partial z} \right] = - \frac{\partial p}{\partial z}$$

$$+ \mu \left[\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial v_z}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 v_z}{\partial \theta^2} + \frac{\partial^2 v_z}{\partial z^2} \right] + \rho g_z$$

$$\frac{\partial p}{\partial z} = \rho g_z \quad \dots (3)$$

pers (2) $\frac{1}{r} \frac{d}{dr} (r v_\theta) = c_1$

$$r v_\theta = c_1 r^2 + c_2$$

$$v_\theta = c_1 r + \frac{c_2}{r}$$

BC:

$$r = KR \quad v_\theta = 0$$

$$r = R \quad v_\theta = \Omega_0 R$$

$$v_\theta = \Omega_0 R \frac{\left(\frac{KR}{r} - \frac{r}{KR} \right)}{\left(K - \frac{1}{K} \right)}$$